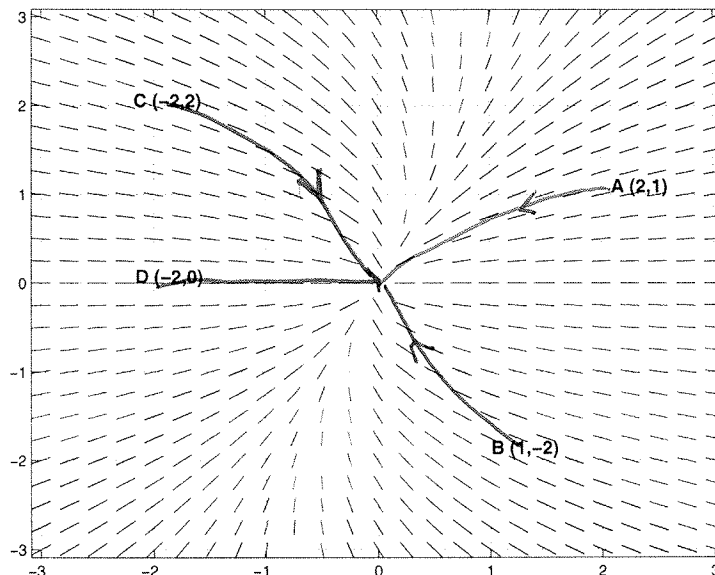


1. Consider the slope field for the given system

$$\begin{aligned}\frac{dx}{dt} &= -2x + \frac{1}{2}y \\ \frac{dy}{dt} &= -y\end{aligned}$$



(a) 1 point. Write the given system of linear ODEs in matrix form  $\frac{d\vec{x}}{dt} = A\vec{x}$ , where  $\vec{x} = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$ .

$$\frac{d\vec{x}}{dt} = \begin{pmatrix} -2 & 1/2 \\ 0 & -1 \end{pmatrix} \vec{x}$$

(b) 4 points. Find the eigenvalues  $\lambda_1$  and  $\lambda_2$  and the eigenvectors  $\vec{v}_1$  and  $\vec{v}_2$  of the matrix  $A$  from part (a) and use that information to write the general solution of the system of linear ODEs in the form  $\vec{x}(t) = c_1 e^{\lambda_1 t} \vec{v}_1 + c_2 e^{\lambda_2 t} \vec{v}_2$

Upper triangular so  $\lambda_1 = -2$  or  $\lambda_2 = -1$

Find  $\text{null}(A - (-2)I) \Rightarrow \begin{pmatrix} 0 & 1/2 & : & 0 \\ 0 & -1 & : & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 & : & 0 \\ 0 & 0 & : & 0 \end{pmatrix} \Rightarrow y=0, x \text{ any}$   
 $\lambda = -2, E_{-2} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$

$\text{null}(A - (-1)I) \Rightarrow \begin{pmatrix} -1 & 1/2 & : & 0 \\ 0 & 0 & : & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & -1 & : & 0 \\ 0 & 0 & : & 0 \end{pmatrix}$   $2x - y = 0$   
 $y = 2x$   $E_{-1} = \begin{pmatrix} x \\ 2x \end{pmatrix} = x \begin{pmatrix} 1 \\ 2 \end{pmatrix}$   
 $x \in \mathbb{R}$

$$\vec{x}(t) = c_1 e^{-t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

(c) 4 points. On the given phase plane, indicate the trajectories for solutions which start at the initial conditions  $A = (2, 1)$ ,  $B = (1, -2)$ ,  $C = (-2, 2)$  and  $D = (-2, 0)$  (USE ARROWS!)

(d) 1 point. Discuss the stability of the equilibrium point (at the origin) of the system. Is the equilibrium stable or un-stable? (HINT: What happens to solutions as  $t \rightarrow \infty$  for each solution curve.)

As  $t \rightarrow \infty, \vec{x}(t) \rightarrow \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  so the origin is STABLE  
 (i.e. a SINK).