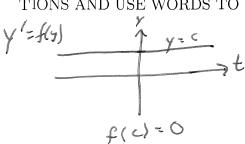
1. (2 points.) What is an equilibrium solution for a 2-dimensional system of differential equations $\frac{d\vec{x}}{dt} = \vec{F}(\vec{x})$ and how does it differ (geometrically) from an equilibrium solution for a differential equation, $\frac{dy}{dt} = f(y)$? (HINT: DRAW PICTURES REPRESENTING THE DIFFERENT SITUA-TIONS AND USE WORDS TO DESCRIBE THEM.)



equiliserum il 12-0 if is 6 (on graphs of 2 lives) マーエレン = Kay.)

2. (2 points.) What are the equilibrium solutions for the standard Lotka-Volterra predator-prey model R' = aR - bRF, F' = -cF + dRF? What is the physical interpretation of these equilibrium \Rightarrow R(a-bE(z0) =) Rzo or <math>F=a/b F(-c+dR)zO = Fzo or <math>RzO/dvalues on the predator F and prey R populations?

are equilibrium sachons R=F=0 is the trivial solution -> no rabbits or fixe R= 71, E. 95 means there exists the to

3. (2 points.) Explain in your own words what the difference between coupled and decoupled harmon systems of equations are. Give an example of each type (linear, first-order, ordinary).

de Coupled equations are autonomous in a single variable Cother depondet Variables do not appear I much easier to solve i.e x'= X, y = y Coupled: rate of change of one variable depends on another eg- x'= y, y'=-x+y dependent reviable

4. (2 points.) What is a reasonable guess for the general solution of y' = -3y + t? [HINT: How

many unknown constants should your solution have?]

y(t) = Yh + Yp = Ae - 3t + Bt + C Should have only one unknown (soutant - Guss: /y = Ae-3+1t-1 V= -3Ae-3++B = -3(Ae-3++B++C)+t $(-3A+3A)e^{-7t}+1\cdot(B+3C)+t(3B-1)=0 \Rightarrow B=\frac{1}{3}$

5. (2 points.) TRUE or FALSE: "Euler's Method can never be used to approximate solutions to a second-order nonlinear ordinary differential equation." EXPLAIN YOUR ANSWER.

False. Write the 2nd order ODE as a 2-0 system of ODEs y"= f(x,y,y') Let u = y v' = f(x,u,v)u'= v = 14/v Given: y(0) = A u(01=A 41(0) : B 1x = F(x) = (+ k,u, v)