

1. Consider the system of ordinary differential equations

$$\frac{d\vec{x}}{dt} = A\vec{x} = \begin{bmatrix} 0 & 2 \\ 0 & -1 \end{bmatrix} \vec{x} \text{ where } \vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

(a) 4 points. Show that the matrix  $A$  has eigenvalues 0 and  $-1$  and eigenvectors which are multiples of  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$ . Write down the general solution of the system.

$$|A - \lambda I| = \begin{vmatrix} -\lambda & 2 \\ 0 & -1-\lambda \end{vmatrix} = \lambda(1+\lambda) = 0 \Rightarrow \lambda = 0 \text{ or } -1$$

$$\lambda = 0 \Rightarrow \begin{pmatrix} 0 & 2 \\ 0 & -1 \end{pmatrix} \Rightarrow \vec{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \vec{x}(t) = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 1 \end{pmatrix} e^{-t}$$

$$\lambda = -1 \Rightarrow \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix} \Rightarrow \vec{x} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

(b) 3 points. Find the exact solution for each of the trajectories which go through the points  $A(1, 1)$ ,  $B(0, -2)$  and  $C(4, 0)$ .

$$A \begin{pmatrix} 1 \\ 1 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 1 \end{pmatrix} \Rightarrow \begin{matrix} c_2 = 1 \\ c_1 = 3 \end{matrix} \quad \vec{x}_A(t) = \begin{pmatrix} 3 - 2e^{-t} \\ e^{-t} \end{pmatrix}$$

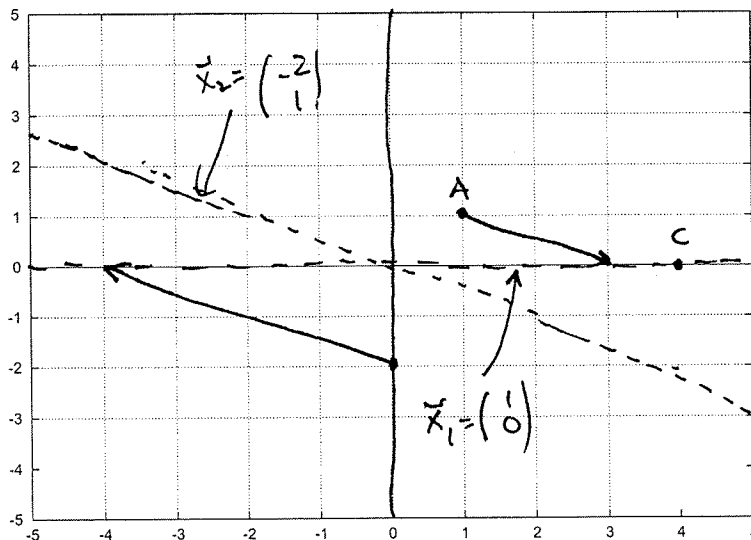
$$B \begin{pmatrix} 0 \\ -2 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 1 \end{pmatrix} \Rightarrow \begin{matrix} c_2 = -2 \\ c_1 = -4 \end{matrix} \quad \vec{x}_B(t) = \begin{pmatrix} -4 + 4e^{-t} \\ -2e^{-t} \end{pmatrix}$$

$$C \begin{pmatrix} 4 \\ 0 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 1 \end{pmatrix} \Rightarrow \begin{matrix} c_2 = 0 \\ c_1 = 4 \end{matrix} \quad \vec{x}_C(t) = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

$$\frac{dx}{dt} = 2y \quad \frac{dy}{dt} = -y \quad \frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{-y}{2y} = -\frac{1}{2} = \frac{dy}{dx} \leftarrow \text{constant slope}$$

(c) 3 points. On the figure below clearly indicate where each of the trajectories of the solutions which start at  $(1, 1)$ ,  $(0, -2)$  and  $(4, 0)$  ends up as  $t \rightarrow \infty$ .

$y = 0$  is equilibrium (static) solution of system



As  $t \rightarrow \infty$   
 $x_A \rightarrow \begin{pmatrix} 3 \\ 0 \end{pmatrix}$   
 $x_B \rightarrow \begin{pmatrix} -4 \\ 0 \end{pmatrix}$   
 $x_C$  always at  $\begin{pmatrix} 4 \\ 0 \end{pmatrix}$