$Differential\ Equations$

Math 340 §2 Fall 2015

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MWF 3:00-3:55pm Fowler 307 http://sites.oxy.edu/ron/math/340/15/

Worksheet 21

TITLE The Trace-Determinant Plane

CURRENT READING Blanchard, 3.7

Homework #10 Assignments due Monday November 2 (* indicates EXTRA CREDIT)

Section 5.1: 3, 4, 5, 8, 18, 20*.

Section 5.3: 2, 9, 12, 13, 14, 18*.

Chapter 5 Review: 1, 2, 6, 7, 8, 9, 11, 12, 26, 27*.

SUMMARY

We shall summarize all the possible equilibria one can get with a 2x2 linear system of ODEs into one big picture!

1. Summarizing The Possibilities

Given a system of linear ODEs with associated matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ the characteristic polynomial is $(a - \lambda)(d - \lambda) - bc = \lambda^2 - (a + d)\lambda + ad - bc = \lambda^2 - \text{tr}(A)\lambda + \text{det}(A) = 0$.

GROUPWORK

Your goal is to match the case # in the left column with the description of its critical point on the right (the list now is jumbled).

CASE 1: Real λ , $\lambda_1 \lambda_2 < 0$

CASE 2: Real λ , $\lambda_1 \& \lambda_2 < 0$

CASE 3: Real λ , $\lambda_1 \& \lambda_2 > 0$

CASE 4: Real λ , $\lambda_1 = \lambda_2 > 0$

CASE 5: Real λ , $\lambda_1 = \lambda_2 < 0$

CASE 6: Complex λ , Re(λ) > 0

CASE 7: Complex λ , Re(λ) < 0

CASE 8: Complex λ , Re(λ) = 0

A Center

B Spiral Source

C (Stable) Node

D(Unstable) Node

E Saddle

F Spiral Sink

G Sink

H Source

Run the LinearPhasePortaits program from the Blanchard, Devaney & Hall textbook software. Use the slide bars to obtain different values of a, b, c and d and the different kinds of eigenvalues recorded above in the Cases. Record your results in the table below.

CASE #	a	b	С	d	λ_1	λ_2	Description
1							
2							
3							
4							
5							
6							
7							
8							

For more details, see the handout from Edwards and Penney, Differential Equations, 3rd Edition, Prentice Hall: 2004, pp 381-389.

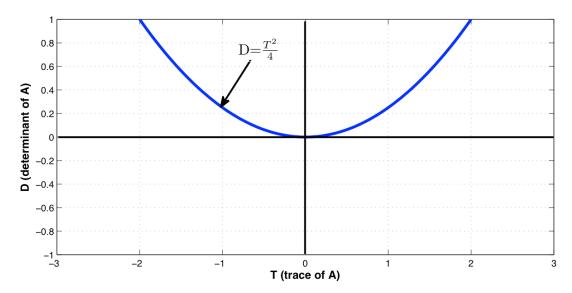
2. The Trace-Determinant Plane

Recall that the eigenvalues of a 2x2 matrix are given by the rootsof the polynomial $p(\lambda) = \lambda^2 - \operatorname{tr}(A)\lambda + \det(A) = 0$.

It's also true that the trace of A, denoted tr(A) is equal to the **sum** of the eigenvalues $\lambda_1 + \lambda_2$. Let's use the symbol T for tr(A). The determinant of A, denoted det(A) is equal to the **product** of the eigenvalues $\lambda_1\lambda_2$. Let's use the symbol D for det(A).

Then we know that the eigenvalues are given by the solutions to $\lambda^2 - T\lambda + D = 0$, or $\lambda = \frac{T \pm \sqrt{T^2 - 4D}}{2}$.

In other words, the condition on whether we will have real, complex or repeated eigenvalues depends on the behavior of the discriminant $\Gamma = T^2 - 4D$. See the figure drawn below. This is known as the **Trace-Determinant Plane**



This graph is an example of a parameter plane. As the matrix A changes it has different values of T and D and the linear system $\frac{d\vec{x}}{dt} = A\vec{x}$ corresponding to that matrix will be located at a different location in (T,D)-space.

Exercise

- $\overline{(1)}$ What kind of phase portraits will exist in (T, D)-space along the D axis?
- (2) What about the T-axis?
- (3) What kind of phase portraits occur along the curve $D = \frac{T^2}{4}$?
- (4) What happens as one moves from the region just above the T-axis (D > 0) to just below the T-axis (D > 0)? Does it matter if T > 0 or T < 0?
- (5) What kinds of solutions exist in the region above the parabola $D = \frac{T^2}{4}$?