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1)(n-(n-1))

 $\approx \frac{1}{2} n^3$.

2.3 Spanning Sets and Linear Independence

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2.3 Spanning Sets and Linear Independence

 $\widehat{\mathbf{1}}$. As in Example 2.18, we want to find scalars x and y such that:

 $x\begin{bmatrix}1\\-1\end{bmatrix}+y\begin{bmatrix}2\\-1\end{bmatrix}=\begin{bmatrix}1\\2\end{bmatrix}$ Expanding, we obtain the system: $x+2y=1\\-x-y=2$

We then row reduce the associated augmented matrix: $\begin{bmatrix} 1 & 2 & 1 \\ -1 & -1 & 2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix}$

So the solution is x = -5, y = 2, and the linear combination is $-5\begin{bmatrix} 1 \\ -1 \end{bmatrix} + 3\begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

(2), As in Example 2.18, we want to find scalars x and y such that:

 $x\begin{bmatrix} 4 \\ -2 \end{bmatrix} + y\begin{bmatrix} -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ Expanding, we obtain the system: 4x - 2y = 2-2x + y = 1

We then row reduce the associated augmented matrix: $\begin{bmatrix} 4 & -2 & 2 \\ -2 & 1 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 4 & -2 & 2 \\ 0 & 0 & 2 \end{bmatrix}$

Since $0 \neq 2$, this system clearly has no solution. So, what do we conclude? We conclude that v is not a linear combination of u_1 and u_2 .

We could have noted $\begin{bmatrix} 4 \\ -2 \end{bmatrix} = -2 \begin{bmatrix} -2 \\ 1 \end{bmatrix}$, while $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ is not a multiple of $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$.

(3) As in Example 2.18, we want to find scalars x and y such that:

 $x\begin{bmatrix}1\\1\\0\end{bmatrix}+y\begin{bmatrix}0\\1\\1\end{bmatrix}=\begin{bmatrix}1\\2\\3\end{bmatrix}$ Expanding, we obtain the system: $x & = 1\\ x+y=2\\ y=3$

Since x = 1 and y = 3 implies $x + y \neq 2$, this system clearly has no solution. Therefore, v is not a linear combination of u_1 and u_2 .

As in Example 2.18, we want to find scalars x and y such that:

 $x\begin{bmatrix}1\\1\\0\end{bmatrix}+y\begin{bmatrix}0\\1\\1\end{bmatrix}=\begin{bmatrix}3\\2\\-1\end{bmatrix} \quad \text{Expanding, we obtain the system:} \quad \begin{array}{ccc} x&=&3\\x+&y&=&2\\y&=&-1 \end{array}$

Since x = 3 and y = -1 implies x + y = 2, those values of x and y are clearly the solution.

So the solution is x = 3, y = -1, and the linear combination is $3 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - 1 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$.

The augmented matrix is $\begin{bmatrix} 1 & -1 & 2 & a \\ 2 & -1 & 1 & b \\ 3 & 0 & -1 & c \end{bmatrix}$, and row reduction produces:

$$\begin{bmatrix} 1 & -1 & 2 & a \\ 2 & -1 & 1 & b \\ 3 & 0 & -1 & c \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 1 & -1 & 2 & a \\ 0 & 1 & -3 & -2a + b \\ 0 & 3 & -7 & -3a + c \end{bmatrix} \xrightarrow{R_1 + R_2} \begin{bmatrix} 1 & 0 & -1 & -a + b \\ 0 & 1 & -3 & -2a + b \\ 0 & 0 & 2 & 3a - 3b + c \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -1 & -a + b \\ -a & b & -a + b \end{bmatrix} \xrightarrow{R_1 + R_3} \begin{bmatrix} 1 & 0 & 0 & (a - b + c)/2 \\ 0 & 1 & 0 & (5a - 7b + 3c)/2 \end{bmatrix}$$

$$\frac{\frac{1}{2}R_3}{\longrightarrow} \begin{bmatrix} 1 & 0 & -1 & -a+b \\ 0 & 1 & -3 & -2a+b \\ 0 & 0 & 1 & (3a-3b+c)/2 \end{bmatrix} \xrightarrow{R_1+R_3} \begin{bmatrix} 1 & 0 & 0 & (a-b+c)/2 \\ 0 & 1 & 0 & (5a-7b+3c)/2 \\ 0 & 0 & 1 & (3a-3b+c)/2 \end{bmatrix}$$

We see that x = (a - b + c)/2, y = (5a - 7b + 3c)/2, and z = (3a - 3b + c)/2. So for any choice of a, b, and c we have:

$$\left(\frac{a-b+c}{2}\right)\begin{bmatrix}1\\2\\3\end{bmatrix}+\left(\frac{5a-7b+3c}{2}\right)\begin{bmatrix}-1\\-1\\0\end{bmatrix}+\left(\frac{3a-3b+c}{2}\right)\begin{bmatrix}2\\1\\-1\end{bmatrix}=\begin{bmatrix}a\\b\\c\end{bmatrix}$$

- We should describe the span of the given vectors (a) geometrically and (b) algebraically.
 - (a) Geometrically, we can see that the set of all linear combinations of $\begin{vmatrix} 2 \\ -4 \end{vmatrix}$ and $\begin{vmatrix} -1 \\ 2 \end{vmatrix}$ is just the line through the origin with $\begin{bmatrix} -1\\2 \end{bmatrix}$ as direction vector. Why do we not have to consider $\begin{bmatrix} 2 \\ -4 \end{bmatrix}$? Because $\begin{bmatrix} 2 \\ -4 \end{bmatrix} = -2 \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.
 - (b) Algebraically, the vector equation of this line is $\begin{vmatrix} x \\ y \end{vmatrix} = \begin{vmatrix} -1 \\ 2 \end{vmatrix} t$. That is just another way of saying that $\begin{vmatrix} x \\ y \end{vmatrix}$ is in the span of $\begin{vmatrix} -1 \\ 2 \end{vmatrix}$. Suppose we want to obtain the general equation of this line. One method is to use the system of equations arising from the vector equation:

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} t \Rightarrow \begin{array}{c} x = -t \\ y = 2t \end{array} \text{ So } y = 2(-x) = -2x \Rightarrow 2x + y = 0.$$

- 2.3 Spanning Set
- 14. We should descri
 - (a) Geometrical is just the li Why do we
 - (b) Algebraicall That is just Suppose we

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One metho

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 - (b) Algebraica

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$$\begin{bmatrix} -b \\ +b \\ b+c \end{bmatrix}$$

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2.3 Spanning Sets and Linear Independence

- We should describe the span of the given vectors (a) geometrically and (b) algebraically.
 - (a) Geometrically, we can see that the set of all linear combinations of $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$ is just the line through the origin with $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$ as direction vector.

 Why do we not have to consider $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$? Because $\begin{bmatrix} 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} 3 \\ 4 \end{bmatrix}$.
 - (b) Algebraically, the vector equation of this line is $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} t$.

 That is just another way of saying that $\begin{bmatrix} x \\ y \end{bmatrix}$ is in the span of $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$.

 Suppose we want to obtain the general equation of this line.

 One method is to use the system of equations arising from the vector equation:

$$\left[\begin{array}{c} x \\ y \end{array}\right] = \left[\begin{array}{c} 3 \\ 4 \end{array}\right] t \Rightarrow \quad \begin{array}{c} x = 3t \\ y = 4t \end{array} \text{ So } y = 4\left(\frac{1}{3}x\right) \Rightarrow 3y = 4x \Rightarrow 4x - 3y = 0.$$

- 15. We should describe the span of the given vectors (a) geometrically and (b) algebraically.
 - (a) Geometrically, we can see that the set of all linear combinations of $\begin{bmatrix} 1\\2\\0 \end{bmatrix}$ and $\begin{bmatrix} 3\\2\\-1 \end{bmatrix}$ is just the plane through the origin with $\begin{bmatrix} 1\\2\\0 \end{bmatrix}$ and $\begin{bmatrix} 3\\2\\-1 \end{bmatrix}$ as direction vectors.
 - (b) Algebraically, the vector equation of this plane is $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = s \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + t \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$.

 That is just another way of saying that $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ is in the span of $\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$.

Suppose we want to obtain the general equation of this plane.

One method is to use the system of equations arising from the vector equation:

We know this system is consistent, since $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ is in the span of $\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$.

So, we must have 2x - y + 4z = 0, giving us the general equation we seek.

Note: Both $\begin{bmatrix} 1\\2\\0 \end{bmatrix}$ and $\begin{bmatrix} 3\\2\\-1 \end{bmatrix}$ are orthogonal to $\begin{bmatrix} 2\\-1\\4 \end{bmatrix}$. Should they be?

 $.\,,\mathbf{u}_k.$

 $v_{j_k}\mathbf{u}_k$, so $+\cdots$

 $egin{aligned} v_{m_k} \mathbf{u}_k) \) \mathbf{u}_2 + \cdots \end{aligned}$

 $\mathbf{u}_{m_k})\,\mathbf{u}_k$

 $\mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$; enough?

2.3 Spanning Sets and Linear Independence

22. The vectors $\mathbf{v_1} = \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix}$ and $\mathbf{v_2} = \begin{bmatrix} 1 \\ 4 \\ 4 \end{bmatrix}$ are linearly independent.

This can be determined by inspection because they are not scalar multiples of each other.

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23. Since there is no obvious dependence relation here, we follow Example 2.23.

Find scalars
$$c_1$$
, c_2 , and c_3 such that: $c_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.

Form the linear system, its associated augmented matrix, and row reduce to solve:

Since $c_1 = c_2 = c_3 = 0$ is the unique solution, the vectors are linearly independent.

24. Since there is no obvious dependence relation here, we follow Example 2.23.

Find scalars
$$c_1$$
, c_2 , and c_3 such that: $c_1\begin{bmatrix}2\\2\\1\end{bmatrix}+c_2\begin{bmatrix}3\\1\\2\end{bmatrix}+c_3\begin{bmatrix}1\\-5\\2\end{bmatrix}=\begin{bmatrix}0\\0\\0\end{bmatrix}$.

Form the linear system, its associated augmented matrix, and row reduce to solve:

Since $c_1 = 4c_3$ and $c_2 = -3c_3$ is a solution, the vectors are linearly dependent.

One dependence relationship is: $4\begin{bmatrix}2\\2\\1\end{bmatrix} - 3\begin{bmatrix}3\\1\\2\end{bmatrix} + \begin{bmatrix}1\\-5\\2\end{bmatrix} = \begin{bmatrix}0\\0\\0\end{bmatrix}$. Are there others?

The vectors
$$\mathbf{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$
, $\mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$ and $\mathbf{v}_3 = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$ are linearly dependent.

This can be determined by inspection because $v_1 - v_2 + v_3 = 0$.

his can be determined by inspection because [A|0] obviously has a nontrivial solution. Why? ecause there are only 3 equations (corresponding to the number of rows), ut there are 4 variables (corresponding to the number of vectors which then become columns). ee Section 2.2, Theorem 2.6 for more detail.

urthermore, this follows immediately from Theorem 2.8. Why? This is a set of 4 vectors in \mathbb{R}^3 . Why does Theorem 2.8 apply? Hint: 4 > 3.

lo find a specific dependence relationship, we follow Example 2.23.

Find scalars
$$c_1$$
, c_2 , and c_3 such that: $c_1 \begin{bmatrix} -2 \\ 3 \\ 7 \end{bmatrix} + c_2 \begin{bmatrix} 4 \\ -1 \\ 5 \end{bmatrix} + c_3 \begin{bmatrix} 3 \\ 1 \\ 3 \end{bmatrix} + c_4 \begin{bmatrix} 5 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.

form the linear system, its associated augmented matrix, and row reduce to solve:

Since $c_1 = \frac{13}{37}c_4$, $c_2 = -\frac{6}{37}c_4$, $c_3 = -\frac{45}{37}c_4$ is a solution, the vectors are linearly dependent.

One dependence relationship is:
$$13\begin{bmatrix} -2\\3\\7 \end{bmatrix} - 6\begin{bmatrix} 4\\-1\\5 \end{bmatrix} - 45\begin{bmatrix} 3\\1\\3 \end{bmatrix} + 37\begin{bmatrix} 5\\0\\2 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}$$
.

The vectors
$$\mathbf{v}_1 = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$$
, $\mathbf{v}_2 = \begin{bmatrix} 6 \\ 7 \\ 8 \end{bmatrix}$, $\mathbf{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ are linearly dependent.

This can be determined by inspection because v_3 is the zero vector. Why is that enough? Because $0v_1 + 0v_2 + v_3 = 0$.

Any set of vectors containing the zero vector is linearly dependent. Why?

Since there is no obvious dependence relation here, we follow Example 2.23.

Find scalars
$$c_1$$
, c_2 , and c_3 such that: $c_1 \begin{bmatrix} -1 \\ 1 \\ 2 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ 2 \\ 2 \\ 4 \end{bmatrix} + c_3 \begin{bmatrix} 2 \\ 3 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$.

Form the linear system, its associated augmented matrix, and row reduce to solve:

Since $c_1 = c_2 = c_3 = 0$ is the unique solution, the vectors are linearly independent.

2.3 Spanning Sets ar

29. Since there is no obvi

Find scalars c_1, c_2, c_3

Form the linear syste

$$c_1 - c_2 + \\ -c_1 + c_2 \\ c_1 + \\ c_2 -$$

Since
$$c_1 = c_2 = c_3 =$$

30. The vectors
$$\mathbf{v_i} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

This can be determine To create a 0 in the Given that, a 0 in the Given those two fact And finally, given all To verify this arguments.

Find scalars c_1 , c_2 , c

Form the linear system

$$3c_{2} + 2c$$

$$4c_{1} + 3c_{2} + 2c$$
Since $c_{1} = c_{2} = c_{3} =$

31. The vectors
$$\mathbf{v}_1 =$$

This can be determi

42. We will use the theorems of Sections 2.2 and 2.3 to support the conclusions below.

(a) Given $A = [\mathbf{v}_1 \ \mathbf{v}_2 \dots \mathbf{v}_n]$, we will show that $\operatorname{rank}(A) = n$.

Theorem 2.6 of Section 2.3 implies:

Vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$ are linearly independent if and only if the only solution of $[A \mid 0] = [\mathbf{v}_1 \ \mathbf{v}_2 \dots \mathbf{v}_n \mid 0]$ is the trivial solution.

Therefore, the number of free variables in the associated system is 0.

So, Theorem 2.2 of Section 2.2 (The Rank Theorem) implies:

number of free variables = $0 = n - \text{rank}(A) \Rightarrow \text{rank}(A) = n$, as claimed.

(b) Given
$$A = \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_n \end{bmatrix}$$
 we will show that $\operatorname{rank}(A) = n$.

Theorem 2.7 of Section 2.3 implies:

Vectors v_1, v_2, \dots, v_n are linearly independent if and only if

the rank of $A = \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_n \end{bmatrix}$ is greater than or equal to n. That is, $\operatorname{rank}(A) \geq n$.

But A has n rows therefore we have $n \leq \operatorname{rank}(A) \leq n \Rightarrow \operatorname{rank}(A) = n$, as claimed.

We apply the definition of linear independence and Examples 2.23 and 2.25 to prove our claims.

(a) We will show that $\mathbf{u} + \mathbf{v}$, $\mathbf{v} + \mathbf{w}$, and $\mathbf{u} + \mathbf{w}$ are linearly independent. Given $c_1(\mathbf{u} + \mathbf{v}) + c_2(\mathbf{v} + \mathbf{w}) + c_3(\mathbf{u} + \mathbf{w}) = 0$, we will show $c_1 = c_2 = c_3 = 0$. Multiplying and gathering like terms yields: $(c_1 + c_3)\mathbf{u} + (c_1 + c_2)\mathbf{v} + (c_2 + c_3)\mathbf{w} = 0$. Since \mathbf{u} , \mathbf{v} , and \mathbf{w} are linearly independent, $c_1 + c_3 = c_1 + c_2 = c_2 + c_3 = 0$. We create the matrix of coefficients A and row reduce to determine its rank:

$$c_{1} + c_{3} = 0 c_{1} + c_{2} = 0 c_{2} + c_{3} = 0$$

$$c_{2} + c_{3} = 0$$

$$c_{3} = 0 c_{4} = 0$$

$$c_{5} = 0 c_{6} = 0$$

$$c_{7} = 0 c_{7} = 0$$

Since rank(A) = 3 the only solution is the trivial one, so $c_1 = c_2 = c_3 = 0$.

(b) We will show that $\mathbf{u} - \mathbf{v}$, $\mathbf{v} - \mathbf{w}$, and $\mathbf{u} - \mathbf{w}$ are linearly dependent. Given $c_1(\mathbf{u} - \mathbf{v}) + c_2(\mathbf{v} - \mathbf{w}) + c_3(\mathbf{u} - \mathbf{w}) = 0$, we will show $c_1 = c_2 = -c_3$. Multiplying and gathering like terms yields: $(c_1 + c_3)\mathbf{u} + (-c_1 + c_2)\mathbf{v} + (-c_2 - c_3)\mathbf{w} = 0$. Since \mathbf{u} , \mathbf{v} , and \mathbf{w} are linearly independent, $c_1 + c_3 = -c_1 + c_2 = -c_2 - c_3 = 0$. We form the augmented matrix and row reduce to solve:

This clearly has the solution $c_1 = c_2 = -c_3$ as we were to show.

44. We will conside

Case 1 Given v_1 :
They are 1
They are 1

Case 2 Assume be To show to we must p

- (a) if two ·
- (b) if two
- (a) Assun Since
- (b) Assur Since we hav So, v₁
- **45.** We will follow t

PROOF: Let .

By Theorem 2.1 By definition, re of row echelon i

So, we have ran

46. Idea: Given any extend it to the

PROOF: Let . By c

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