Basis, Dimension, Rank

A <u>basis</u> for a subspace S of \mathbb{R}^n is a set of vectors in S that

- 1. span S
- 2. are linearly independent

An example of a basis is $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$, which spans \mathbb{R}^n and is linearly independent. This is called the **standard basis** of \mathbb{R}^n .

Example:

Find a basis for row(A), col(A) and null(A), where

 $A = \begin{bmatrix} 1 & -2 & 1 & 4 \\ -1 & 2 & 1 & 2 \\ 2 & -4 & 0 & 2 \end{bmatrix}.$

In general, to find a basis for row(A), col(A) and null(A), do the following:

- 1. Find the reduced row echelon form R of A.
- 2. The nonzero row vectors of R form a basis for row(A).
- 3. The column vectors of A corresponding to columns of R with leading 1's (the pivot columns) form a basis for col(A).
- 4. Solve for the leading variables of $R\mathbf{x} = \mathbf{0}$ in terms of the free variables. Write the solution \mathbf{x} as a column vector expanded into a linear combination with the free variables being the coefficients. The vectors in terms of which the linear combination is written form a basis for null(A).

Although the same subspace can have many different bases, the number of vectors in each must be the same.

<u>**Theorem</u>**: Let S be a subspace of \mathbb{R}^n . Then the number of vectors in any basis of S is the same and is called the <u>**dimension**</u> of S.</u>

For the row and column space of a matrix the following property holds.

<u>**Theorem**</u>: The row and column space of a matrix A have the same dimension.

The **<u>rank</u>** of a matrix A, denoted rank(A), is the dimension of its row and column spaces. The **nullity** of a matrix A, denoted nullity(A), is the dimension of its null space.

It is easy to see that $rank(A^T) = rank(A)$. The rank and the nullity of a matrix have the following relation.

<u>The Rank Theorem</u>: If A is an $m \times n$ matrix, then

 $\operatorname{rank}(A) + \operatorname{nullity}(A) = n.$

The fundamental theorem for invertible matrices can be now extended using some of these new notions.

<u>The Fundamental Theorem for Invertible Matrices</u>: Let A be an $n \times n$ matrix. The following are equivalent.

- (a) A is invertible
- (b) $A\mathbf{x} = \mathbf{b}$ has a unique solution for every \mathbf{b} in \mathbb{R}^n .
- (c) $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
- (d) The reduced row echelon form of A is I_n .
- (e) A is a product of elementary matrices.
- (f) $\operatorname{rank}(A) = n$.
- (g) nullity(A) = 0.
- (h) The column vectors of A are linearly independent.
- (i) The column vectors of A span \mathbb{R}^n .
- (j) The column vectors of A form a basis for \mathbb{R}^n .
- (k) The row vectors of A are linearly independent.
- (1) The row vectors of A span \mathbb{R}^n .
- (m) The row vectors of A form a basis for \mathbb{R}^n .

An application of the Rank Theorem and the Fundamental theorem gives the following.

<u>Theorem</u>: Let A be an $m \times n$ matrix. Then:

- (a) $\operatorname{rank}(A^T A) = \operatorname{rank}(A)$.
- (b) The $n \times n$ matrix $A^T A$ is invertible if and only if rank(A) = n.

Exercises:

1. Determine whether the following vectors form a basis for \mathbb{R}^3 .

[1]		$\begin{bmatrix} -2 \end{bmatrix}$		[1]
-1	,	1	,	1
2		-5		4