Mathematical Modeling

Math 396 Fall 2008 ©2008 Ron Buckmire

Fowler 110 Thu 1:30- 2:55pm http://faculty.oxy.edu/ron/math/396/08/

Week 2: Thursday September 4

TITLE Modeling Using Proportionality **CURRENT READING** Giordano, 2.2

SUMMARY

Let's start our reviews of various types of modelling by reviewing models that involve proportionality and model fitting (using least squares).

DEFINITION: proportionality

Two variables y and x are **proportional** (to each other) if one is always a constant multiple of the other." (Giordano, Weir & Fox, page 2.) We denote this relationship as $y \propto x$ if and only if y = kx where k is a non-zero constant.

Consider the following table of "famous proportionalities."

Hooke's Law: F = kS, where F is the restoring force in a spring stretched or compressed a distance S.

Newton's Law: F = ma, where a is the acceleration of a mass m subject to an external force F.

Ohm's Law: V = iR where *i* is the current induced by a voltage *V* across a resistance *R*. **Boyle's law:** $V = \frac{k}{p}$, where under a constant temperature, the volume *V* of an ideal gas is proportional to the pressure *p*.

Einstein's theory of relativity: $E = mc^2$, where the energy E equivalent of a mass m is proportional with constant c^2 , the speed of light squared.

Kepler's third law: $T = cR^{3/2}$, where T is the period (in days) and R is the mean distance to the sun.

Problem

Consider the data in S:\Math Courses\Math396\Kepler.xls. Try to obtain a value for the constant of proportionality c in Kelper's Third Law. (What are your units?)

Approximation Theory

In approximation theory we have a set of m data points (x_k, y_k) for which we do not know what the actual function f(x) which reflects the relationship between the input variable xand the output y.

Suppose we define the **deviation** as $\delta_k = P(x_k) - y_k$ and find a function P(x) such that the total deviations between the function P(x) and the data points (x_k, y_k) is minimised. There is more than one way to do this.

We define a function E which represents the total deviation we are trying to minimize and we want to find P which minimizes E, where E can have different forms.

Some Ways To Formulate E Are:

$$E_1 = \sum_{k=1}^{m} |P(x_k) - y_k|$$

OR

$$E_{\infty} = \max_{1 \le k \le m} |P(x_k) - y_k|$$

OR

$$E_2 = \sum_{k=1}^{m} [P(x_k) - y_k]^2$$

From statistics we know that if the data are **normally distributed** then the square error (E_2) is the best form of the error to use to measure how well P(x) is approximating the unknown function f(x) represented by the data y_k .

Linear Fit

If we assume that the polynomial we choose for P(x) is linear so that P(x) = ax + b then the problem of finding P becomes a minimization problem. If we consider E is a function of the parameters a and b what it the problem we have to solve?

Therefore

$$a = \frac{\overline{xy} - \overline{x} \cdot \overline{y}}{\overline{x^2} - \overline{x}^2} \qquad b = \frac{\overline{x^2} \cdot \overline{y} - \overline{xy} \cdot \overline{x}}{\overline{x^2} - \overline{x}^2}$$

The line P(x) = ax + b is known as the "least squares" line, or "line of best fit" or "regression line"

Example

Consider the following data from Table 3.3 of Giordano, Fox & Weir.

x_i	y_i	x_i^2	$x_i y_i$	$P(x_i)$	$ y_i - P(x_i) $
0.5	0.7				
1.0	3.4				
1.5	7.2				
2.0	12.4				
2.5	20.1				

Problem

Attempt to predict the value of the variable y when x = 2.25 assuming a relationship of $y = Ax^2$.

Fitting Data to Nonlinear Functions: OR Making Nonlinear Relationships Appear Linear

Isn't there some way we could transform the equation $y = be^{ax}$ and $y = bx^a$ so that a linear relationship would appear? Then we could use our previously defined normal equations of least-squares fit for a line.

Think about introducing some new variables Y and X such that there is a linear relationship between Y and X even though y and x are non-linearly related.

A Harder One

How could you pick Y and X so that you could solve the normal equations and fit data to $y = \alpha x e^{\beta x}$?