

1. In class we found one of the points of intersection of the hyperbola $4x^2 - y^2 = 1$ and the circle $(x-1)^2 + y^2 = 2^2$ to be $(1.1165151, 1.9966032)$.

Let $g_1(x, y) = \frac{8x - 4x^2 + y^2 + 1}{8}$ and $g_2(x, y) = \frac{2x - x^2 + 4y - y^2 + 3}{4}$ where $\vec{G}(\vec{x}) = \begin{bmatrix} g_1(x, y) \\ g_2(x, y) \end{bmatrix}$

- (a) [1 pt] Show that the fixed point(s) of the vector function $\vec{G}(\vec{x})$ are exactly the points of intersection of the hyperbola $4x^2 - y^2 = 1$ and circle $(x-1)^2 + y^2 = 4$. (HINT: one way to do this is to show algebraically that the fixed points of \vec{G} satisfy the exact same equation that the points of intersection do.)

$$\begin{aligned} x &= \frac{8x - 4x^2 + y^2 + 1}{8} & y &= \frac{2x - x^2 + 4y - y^2 + 3}{4} \\ 8x &= 8x - 4x^2 + y^2 + 1 & 4y &= 2x - x^2 + 4y - y^2 + 3 \\ 0 &= -1 + 4x^2 - y^2 & 0 &= -(x^2 - 2x + 1) - y^2 + 4 \\ 1 &= 4x^2 - y^2 & (x-1)^2 + y^2 &= 4 \end{aligned}$$

- (b) [2 pts] Starting with an initial guess of $\vec{x}_0 = (1, 2)^T$ compute the next approximation to the fixed point of \vec{G} using Successive Substitution, $\vec{x}_k = \vec{G}(\vec{x}_{k-1})$

$$\vec{x}_1 = \begin{pmatrix} g_1(1, 2) \\ g_2(1, 2) \end{pmatrix} = \begin{pmatrix} \frac{8 \cdot 1 - 4 \cdot 1^2 + 2^2 + 1}{8} \\ \frac{2 \cdot 1 - 1^2 + 4 \cdot 2 - 2^2 + 3}{4} \end{pmatrix} = \begin{pmatrix} 9/8 \\ 2 \end{pmatrix}$$

- (c) [2 pts] Starting with an initial guess of $\vec{x}_0 = (1, 2)^T$ compute the next approximation to the fixed point of \vec{G} using Seidel Iteration.

$$\begin{aligned} x^{(1)} &= g_1(1, 2) = 9/8 & y^{(1)} &= g_2(9/8, 2) = \frac{2 \cdot 9/8 - (9/8)^2 + 4 \cdot 2 - 2^2 + 3}{4} \\ & & &= \frac{18/8 - 81/64 + 8 - 4 + 3}{4} = 1.996 \end{aligned}$$

- (d) [2 pts] Considering $\vec{f}(\vec{x}) = \begin{bmatrix} 4x^2 - y^2 - 1 \\ (x-1)^2 + y^2 - 2^2 \end{bmatrix}$ Find the Jacobian matrix $J(x, y)$ for the system.

$$J(x, y) = \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix} = \begin{pmatrix} 8x & -2y \\ 2x-2 & 2y \end{pmatrix}$$

- (e) [3 pts] Starting with an initial guess of $\vec{x}_0 = (1, 2)^T$ compute the next approximation to the fixed point of \vec{G} (which is also the root of \vec{f}) using Newton's Method.

$$\begin{aligned} J(1, 2) \cdot \Delta \vec{x} &= -\vec{f}(1, 2) \\ \begin{pmatrix} 8 & -4 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} &= -\begin{pmatrix} 4 \cdot 1^2 - 2^2 - 1 \\ 0^2 + 2^2 - 2^2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} & \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix} &= \begin{pmatrix} 1/8 & 1/8 \\ 0 & 1/4 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/8 \\ 0 \end{pmatrix} \\ J^{-1}(1, 2) &= \frac{1}{8 \cdot 4 - 0 \cdot (-4)} \begin{pmatrix} 4 & 4 \\ 0 & 8 \end{pmatrix} = \begin{pmatrix} 1/32 & 1/32 \\ 0 & 1/32 \end{pmatrix} & \begin{pmatrix} x^{(1)} \\ y^{(1)} \end{pmatrix} &= \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1/8 \\ 0 \end{pmatrix} = \begin{pmatrix} 9/8 \\ 2 \end{pmatrix} \end{aligned}$$

You may have to attach/staple an extra sheet with your calculations on it to support your answers.