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# Linear Systems

Math 214 Spring 2006  
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Fowler 307 MWF 2:30pm - 3:25pm  
<http://faculty.oxy.edu/ron/math/214/06/>

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## Class 5: Wednesday February 1

**SUMMARY** Understanding Linear Systems of Equations

**CURRENT READING** Poole 2.1

### OUTLINE

Today we will discover different ways of looking at linear systems and discover an interesting fact common to **all** linear systems.

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### Homework Assignment

HW #5: Section 1.3: 7, 14, 18, 27, 29; EXTRA CREDIT 25: DUE FRI FEB 3

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Consider the vectors  $\vec{v} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$  and  $\vec{w} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$

One of the central ideas of this *Linear Systems* course concerns Linear Combinations of Vectors.

One of the basic questions is when does a linear combination of vectors equal another vector? In other words, can you find a linear combination of  $\vec{v}$  and  $\vec{w}$  such that

$$c\vec{v} + d\vec{w} = \begin{bmatrix} 6 \\ 2 \end{bmatrix}?$$

OR

$$c\vec{v} + d\vec{w} = \begin{bmatrix} 7 \\ 7 \end{bmatrix}?$$

OR

$$c\vec{v} + d\vec{w} = \text{any } 2 \times 1 \text{ vector?}$$

NOTE: If we take **ALL** linear combinations of  $\vec{v}$  and  $\vec{w}$  we can produce every vector in the entire plane.

What's the relationship between this and solving systems of equations? We could write the problem above as a **linear system**

$$3c + d = 7$$

$$c + 5d = 7$$

(row form)

OR

$$c \begin{bmatrix} 3 \\ 1 \end{bmatrix} + d \begin{bmatrix} 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 7 \\ 7 \end{bmatrix}$$

(column form)

**GROUPWORK**

Solve one of the following systems of equations.

**System A.**

$$\begin{aligned} 2x - y &= 1 \\ -4x + 2y &= 2 \end{aligned}$$

**System B.**

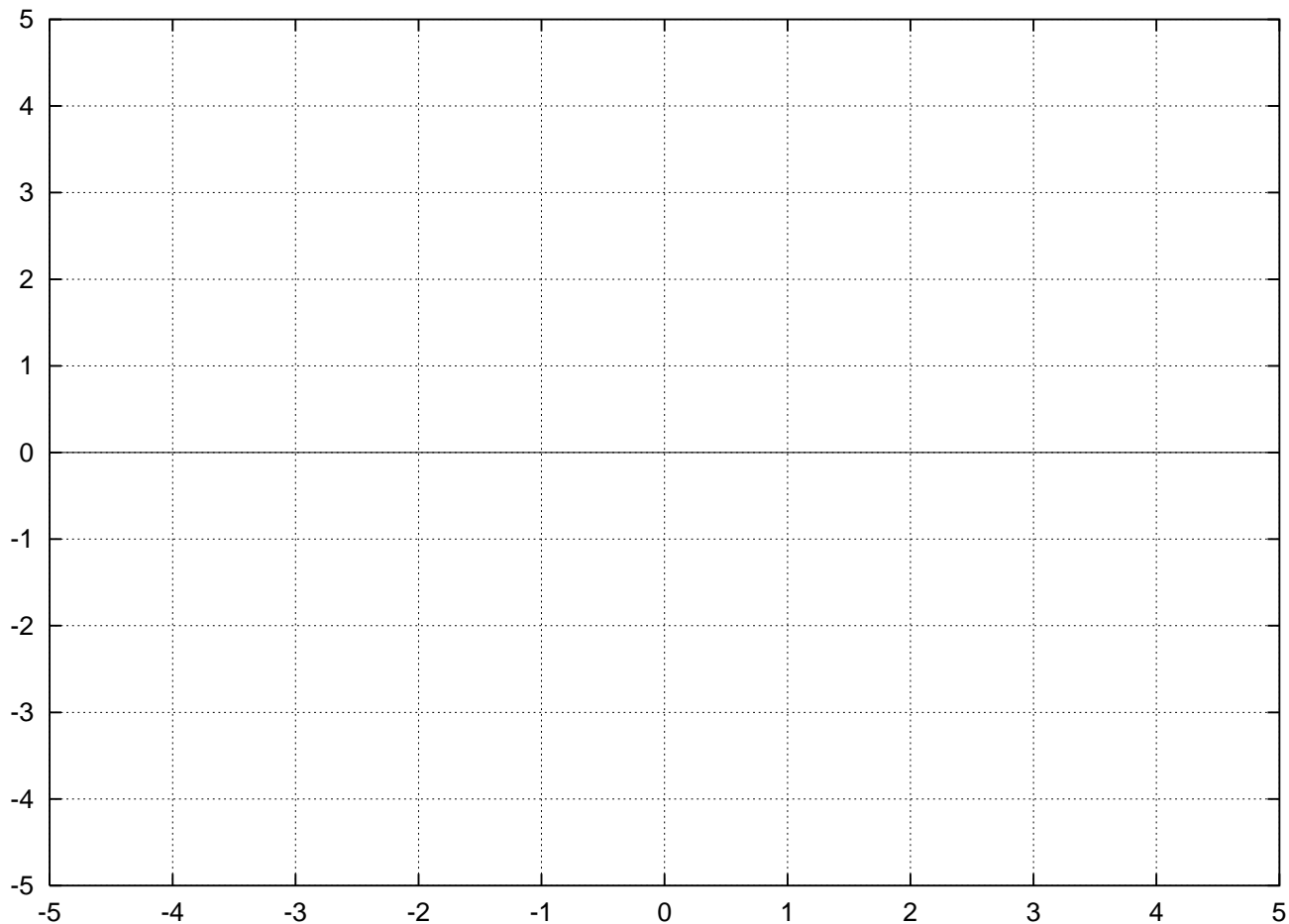
$$\begin{aligned} 2x - y &= 1 \\ -4x + y &= 2 \end{aligned}$$

**System C.**

$$\begin{aligned} 2x - y &= 1 \\ -6x + 3y &= -3 \end{aligned}$$

Let's graph each of the above systems of equations on the  $xy$ -plane below.

**Q:** Before doing so, what do you *expect* to see? What **do** you see?



## 1. Algebraic and Geometric Interpretations of Linear Systems

$$\begin{aligned}4x - y &= 4 \\2x - 3y &= -5\end{aligned}$$

The above is called the **row form** of the system of equations.

Geometrically, the row form can be viewed as:

$$x \begin{bmatrix} 4 \\ 2 \end{bmatrix} + y \begin{bmatrix} -1 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ -5 \end{bmatrix}$$

The above is called the **column form** of the system of equations.

Geometrically, the column form can be viewed as:

$$\begin{bmatrix} 4 & -1 \\ 2 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4 \\ -5 \end{bmatrix}$$

The above is called the **matrix form** of the system of equations.

Geometrically, the matrix form can be viewed as:

### Warm-up

Consider 2 random lines in 2-dimensional space (the regular Cartesian plane). What are the possible scenarios these two random lines can produce? Draw pictures below:

Consider 2 random **planes** in 3-dimensional space. What are the possible scenarios these 2 random planes can produce? Write them down below.

Consider 3 random planes in 3-dimensional space. What are the possible scenarios these 3 planes can produce? Write them below.

### DISCUSSION

What is the connection between the above scenarios and the question of when a linear system of equations has a unique solution? Or no solution?

### DEFINITION: **consistent**

If a system of linear equations has at least one solution then it is called a **consistent** linear system. Otherwise, it is called an **inconsistent** linear system.

### DEFINITION: **singular**

If a system of linear equations does not have a unique solution then it is called a **singular** linear system. Otherwise, it is called an **non-singular** linear system.