

*Definition 1.* Given any mtx  $A$ , the set of all vectors  $\vec{x}$  that satisfy  $A\vec{x} = \vec{0}$  is called the **nullspace** of  $A$ , denoted  $\text{NS}(A)$ . (Book uses boldface N.)

*Example 1.* Let  $A = \begin{bmatrix} 1 & 3 & 0 \\ 2 & 6 & 1 \\ -1 & -3 & 4 \end{bmatrix}$ . Find  $\text{NS}(A)$ .

We need to find all solutions to  $A\vec{x} = \vec{0}$ . Augment  $A$  with a 4th col of zeros. Use Gaussian elimination.

$$\text{row2}=\text{row2}-2\text{row1}, \text{row3}=\text{row3}+\text{row1} \rightarrow \left[ \begin{array}{ccc|c} 1 & 3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 4 & 0 \end{array} \right], \text{row3}=\text{row3}-4\text{row2} \rightarrow U = \left[ \begin{array}{ccc|c} 1 & 3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

So  $z = 0$ , and  $x + 3y = 0$ . Pick  $y$  as our free variable. So the set of all solutions is: all vectors of the form  $\begin{bmatrix} -3y \\ y \\ 0 \end{bmatrix}$ . We call this set of vectors  $\text{NS}(A)$ .

If we let  $y = 1$ , then  $x = -3$ , so we get one solution:  $(-3, 1, 0)$ . Any other solution will be a multiple of this one. Why?

So we call this solution a *special* solution (even though there isn't really anything special about it!).

So  $\text{NS}(A) = \{\vec{v} \mid \vec{v} = c(-3, 1, 0) \text{ for some scalar } c\}$ .

**Q:** Do  $U$  and  $A$  have the same nullspace? **Ans:** Yes, because  $A\vec{x} = \vec{0}$  and  $U\vec{x} = \vec{0}$  have the same solutions. Why?

**Q:** Which row operations do or do not change the solutions to  $A\vec{x} = \vec{b}$ ? **Ans:** None of the row ops change the sols. Why? We've seen this before; row operations are "reversible".

*Theorem 1.* Row operations do not change the nullspace of a mtx. Col operations do not change the column space of a mtx.

*Proof:* Challenge problem.

**Q:** Is  $\text{NS}(A)$  a vector space? For every matrix  $A$ ? For some but not all? **Ans:** Yes, for all matrices.

*Example 2.* Let  $A$  be a square mtx with nonzero det. Make up an example. Find  $\text{NS}(A)$ . **Ans:** The **trivial vector space**  $\{\vec{0}\}$  (it contains only the zero vector). Why?

*Theorem 2.* For any matrix  $A$ ,  $\text{NS}(A)$  is a vector space.

*Proof.* ... □

*Example 3.* Let  $A = \begin{bmatrix} 1 & 3 & 0 & -2 \\ 2 & 6 & 1 & -4 \\ -1 & -3 & 4 & 2 \end{bmatrix}$ . Find  $\text{NS}(A)$ .

We need to find all solutions to  $A\vec{x} = \vec{0}$ . Augment  $A$  with a 5th col of zeros.

$$\text{Do: row2}=\text{row2}-2\text{row1}, \text{row3}=\text{row3}+\text{row1}; \text{ we get: } \left[ \begin{array}{cccc|c} 1 & 3 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 4 & 0 & 0 \end{array} \right].$$

Do: row3=row3-4row2; we get: 
$$\left[ \begin{array}{cccc|c} 1 & 3 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right].$$

So  $x + 3y + 0z + w = 0$ , and  $z = 0$ . What shall we pick as the free variables?  $w$  and  $y$ .

So  $x = -3y - w$ ; and  $z = 0$ . So general solution is of the form 
$$\begin{bmatrix} -3y - w \\ y \\ 0 \\ w \end{bmatrix}.$$

So  $\text{NS}(A)$  = all vectors of the form 
$$\begin{bmatrix} -3y - w \\ y \\ 0 \\ w \end{bmatrix}.$$

Q: Can you find a few specific solutions such that all the above solutions are lin combs of the specific ones you found? Our book calls them **special solutions**. Find them as follows:

Finding the “special solutions”: One at a time, let each of the free variables equal 1, and the rest zero.

We picked  $w$  and  $y$  as free variables. So once let  $y = 1, w = 0$ , and another time do the opposite, let  $y = 0, w = 1$ . For each case, find  $x$  and  $z$ . These give two “special solutions”.

Book writes: **Complete Solution** =  $y$  times special sol #1 +  $w$  times special sol #2.

Q: Is every vector in  $\text{NS}(A)$  a lin comb of these two special sols? Why?

### Echelon form

Recall: after doing Gaussian Elimination, the matrix is in what form? Ans: Upper triangular.

Actually, “upper triangular” is not specific or descriptive enough. For example, consider:  $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 1 & 6 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$

Q: Is  $A$  upper triangular? Yes.

Q: Is  $A$  a matrix one might obtain after doing Gaussian Elimination? No. Why?

Q: Let  $B = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 0 & 5 \\ 0 & 0 & 1 & 6 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$  Is  $B$  upper triangular? Yes. Is  $B$  a matrix one might obtain after doing

Gaussian Elimination? No. Why?

Q: Let  $C = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$  Is  $B$  upper triangular? Yes. Is  $B$  a matrix one might obtain after doing

Gaussian Elimination? Yes.

The shape of matrices one always obtains after Gaussian Elimination is called *echelon form*. Roughly speaking, it means “staircase form”. (Echelon comes from old French, meaning rung of a ladder.)

To give a precise def for echelon form, first recall the def of **pivot**: the first non-zero entry in each row.

*Definition 2.* A matrix is in **echelon form** iff:

1. under every pivot the entries are all zeros; and
2. the pivots are in a “staircase” arrangement, i.e., if  $p$  is a pivot, then every pivot to the right of  $p$  is

below  $p$  (more precisely, for any two pivots  $A_{i,j}$  and  $A_{k,l}$ ,  $i < k$  iff  $j < l$ ); and

3. all rows of zeros appear at the bottom, i.e., below all pivots.

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After Gaussian Elimination, if we continue with back-elimination, we obtain:

*Definition 3.* A matrix is in **reduced row echelon form (rref)** iff:

1. it is in echelon form; and
2. the entries above each pivot are zero; and
3. all pivots equal 1.

*Note.* Our book sometimes just says “reduced form”, instead of “reduced row echelon form.”

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## HW # 14

Read sec 3.2.

Do: p. 118: 1-4,9,11,12, 16,17,19.

Always prove or explain all your answers, even if the book doesn't ask for it!