

---

Examples of applications of matrix multiplication (not in book)

*Example 1.* We have two bags of trail-mix, each containing almonds and raisins. Bag 1: 90% almonds, 10% raisins. Bag 2: 20% almonds, 80% raisins. Let's denote this by the matrix  $A = \begin{bmatrix} .9 & .1 \\ .2 & .8 \end{bmatrix}$ . Suppose almonds contain 60% protein, 40% fat and carbohydrates, while raisins contain 0% protein, 100% fat and carbohydrates; Let's denote this by  $B = \begin{bmatrix} .6 & .4 \\ 0 & 1 \end{bmatrix}$ .

Q1: Compute  $AB$ . What does each entry of  $AB$  represent? Why?

Q2: Suppose we want to make a third bag containing almonds and raisin 50-50. What percentage of bag 3 should come from each of the two bags? Hint: Fill in the details, and give explanations: Let  $x_i$  represent the percentage of bag 3 that comes from bag  $i$ . Then:  $\text{row}_1(A)x_1 + \text{row}_2(A)x_2 = [.5 \ .5]$ ; explain why. So  $A^T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = ?$  Why? So  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = ?$  Why?

---

*Example 2. Rotation Matrices.* Let  $\vec{v} = \begin{bmatrix} x \\ y \end{bmatrix}$  be an arbitrary vector in  $\mathbb{R}^2$ . Let  $A = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$ , where  $\alpha$  is some arbitrary angle in radians. Any  $2 \times 2$  matrix that can be written in this form is called a **rotation matrix**.

Q1: Let  $\vec{w} = A\vec{v}$ . How is  $\vec{w}$  related to  $\vec{v}$ ? A:  $\vec{w}$  is obtained by rotating  $\vec{v}$  counterclockwise through an angle of  $\alpha$ .

*Proof.* We can write  $x$  and  $y$  as:  $x = r \cos(\theta)$ ,  $y = r \sin(\theta)$ . Then  $A\vec{v} = \begin{bmatrix} \cos(\alpha)r \cos(\theta) - \sin(\alpha)r \sin(\theta) \\ \sin(\alpha)r \cos(\theta) + \cos(\alpha)r \sin(\theta) \end{bmatrix} = \begin{bmatrix} r \cos(\theta + \alpha) \\ r \sin(\theta + \alpha) \end{bmatrix}$ , as desired.

□

Q2: Let  $B = \begin{bmatrix} \cos \beta & -\sin \beta \\ \sin \beta & \cos \beta \end{bmatrix}$ , where  $\beta$  is also some arbitrary angle. Is  $AB$  a rotation matrix? A: Yes. Why?

Q3: What is  $A^{-1}$ ? Is it a rotation matrix of angle  $-\alpha$ ? A: Yes. Why?

---

*Example 3.* (From *Elementary Linear Algebra*, by Spence, Insel, and Friedberg, page 108.) We have four cities with airports. Let  $A$  be the  $4 \times 4$  matrix defined by

$$A_{i,j} = \begin{cases} 1 & \text{if there is a nonstop flight} \\ & \text{from city } i \text{ to city } j \\ 0 & \text{otherwise} \end{cases}$$

Q1: Suppose  $A = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$  Compute  $A^2$ . What does  $A^2_{2,3}$  represent? A: It represents the number of flights with exactly one layover between city 2 and city 3. Why?

(Can we do more? Does  $A^3$  represent the flights with exactly two layovers? Why?)

---